



# ***RSF Elektronik***

[www.rsf.at](http://www.rsf.at)

## MC 15 ABSOLUTE EXPOSED LINEAR ENCODERS





- Absolute Position valuation
- Large mounting tolerances
- Serial interfaces
- Status display directly at the scanning head via LED function

## ABSOLUTE MEASUREMENT PRINCIPLE

This means the position valuation from evaluating one unique code information at any point over the entire measuring length. For this the scanning head needs not to be moved relative to the graduation carrier, so that the position value is available immediately after power-on. Reference points and reference drives are thus not required. The subsequent electronics may access this position value at any time.

## REQUIREMENTS ON AN ABSOLUTE LINEAR ENCODER

- AVOIDING REFERENCING
- ADVANCED OPERATIONAL SAFETY
- HIGH TRAVERSING SPEED
- SMALL DIMENSIONS
- NO MECHANICAL BACKLASH
- ZERO FRICTIONAL FORCE
- WEAR-FREE OPERATION

## TERM EXPLANATIONS

### Absolute position indexing

Serial encoding of a line sequence as a highly precise graduation.

### Scanning head

Opto-electronic scanning device of a graduation.

### Yaw angle, pitch angle, roll angle, displacement, gap tolerance

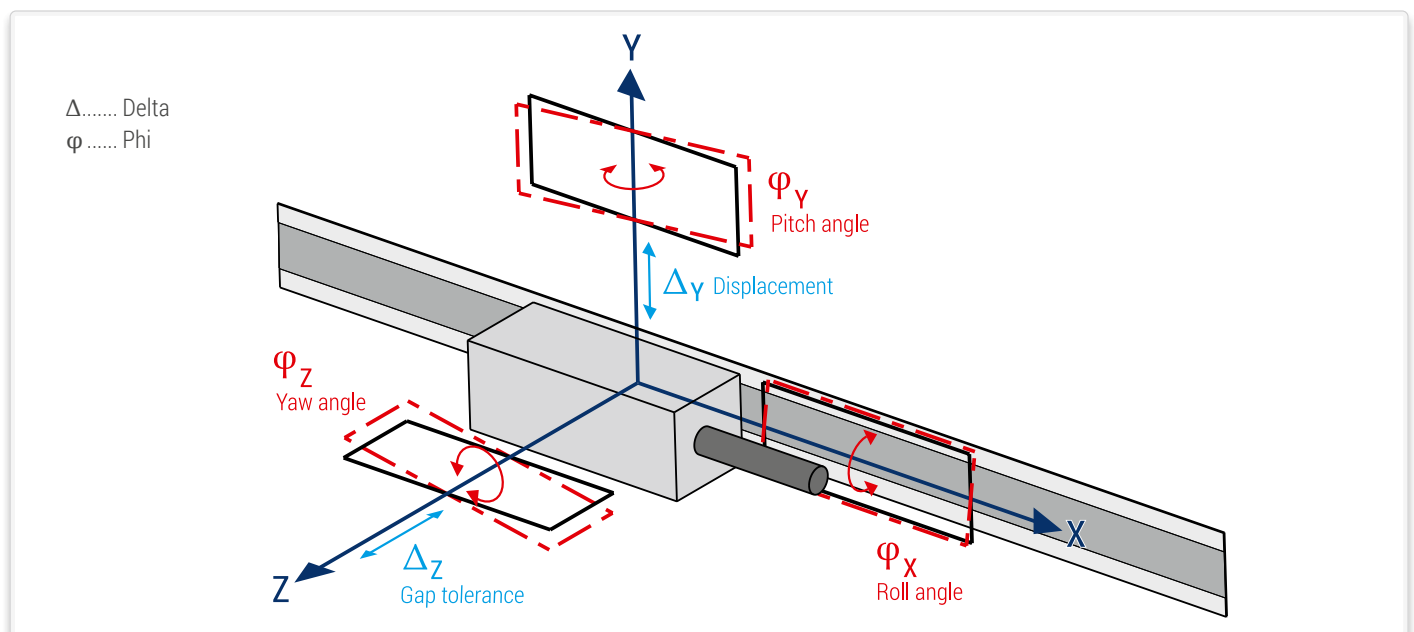
Mounting tolerances of the scanning head relative to the graduation carrier.

### Accuracy

This is a fundamental characteristic, which is specified with an accuracy grade (e.g.  $\pm 5 \mu\text{m/m}$ ).

### Measuring step

The smallest digital counting step produced by an encoder.





# PIN ASSIGNMENTS

**Coupling M12, male, 8-pin** according to IEC 61076-2-101 LM008-Gxx-A





**D-sub connector, male, 15-pin**





EnDat 2.2	Voltage supply				Absolute position values			
	8	2	5	1	3	4	7	6
	4	12	2	10	5	13	8	15
EnDat 2.2	Up	Sensor Up	0 V	Sensor 0 V	DATA	DATA	CLOCK	CLOCK
	Brown/Green	Blue	White/Green	White	Grey	Pink	Violet	Yellow



## BiSS C

	8	2	5	1	3	4	7	6
	4	12	2	10	5	13	8	15
BiSS/Cu	Up	Sensor Up	0 V	Sensor 0 V	SLO+	SLO-	MA+	MA-
	Brown/Green	Blue	White/Green	White	Grey	Pink	Violet	Yellow



## Fanuc

	8	2	5	1	3	4	7	6
	4	12	2	10	5	13	8	15
Fanuc05 ai Interface	Up	Sensor Up	0 V	Sensor 0 V	Serial Data	Serial Data	Request	Request
	Brown/Green	Blue	White/Green	White	Grey	Pink	Violet	Yellow



## Mitsubishi

	8	2	5	1	3	4	7	6
	4	12	2	10	5	13	8	15
Mit03-4	Up	Sensor Up	0 V	Sensor 0 V	Serial Data	Serial Data	Request Frame	Request Frame
Mit03-2					Occupied *	Occupied *	Request/ Data	Request/ Data
	Brown/Green	Blue	White/Green	White	Grey	Pink	Violet	Yellow

## Panasonic

	8	2	5	1	3	4	7	6
	4	12	2	10	5	13	8	15
Pana02	Up	Sensor Up	0 V	Sensor 0 V	Occupied *	Occupied *	Request/ Data	Request/ Data
	Brown/Green	Blue	White/Green	White	Grey	Pink	Violet	Yellow

## Yaskawa

	8	2	5	1	3	4	7	6
	4	12	2	10	5	13	8	15
YEC07	Up	Sensor Up	0 V	Sensor 0 V	Occupied *	Occupied *	DATA	DATA
	Brown/Green	Blue	White/Green	White	Grey	Pink	Violet	Yellow

- Up = Power supply voltage
- Sensor: The sensor line is connected in the scanning head with the corresponding power line.
- The shield is connected with the chassis.
- Not connected pins or wires must not be used.
- \* Required for adjustment/inspection by PWT 101.

## SERIAL INTERFACES

### EnDat 2.2

The EnDat interface is a digital, **bidirectional** interface for encoders. It is capable both of transmitting **position values** as well as transmitting or updating information stored in the encoder, or of saving new information. Thanks to the **serial transmission method**, only **four signal lines** are required. The data is transmitted in **synchronism** with the clock signal from the subsequent electronics. The type of transmission (position values, parameters, diagnostics, etc.) is selected through mode commands that the subsequent electronics send to the encoder.

### CLOCK FREQUENCY

The clock frequency is variable—depending on the cable length (max. 150 m)—between 100 kHz and 2 MHz. With propagation-delay compensation in the subsequent electronics, either clock frequencies up to 16 MHz are possible or cable lengths up to 100 m. The maximum clock frequency is stored in the encoder memory.

EnDat 2.2	≤ 8 MHz or 16 MHz
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Transmission frequencies up to 16 MHz in combination with large cable lengths place high technological demands on the cable. Due to the data transfer technology, the cable connected directly to the encoder must not be longer than 20 m. Greater cable lengths can be realized with a cable no longer than 6 m and an extension cable. As a rule, the entire transmission path must be designed for the respective clock frequency.

### POSITION VALUES

The position value can be transmitted with or without additional data. It is not transmitted to the subsequent electronics until after the calculation time  $t_{cal}$  has passed. The calculation time is ascertained at the highest clock frequency permissible for the encoder, but limited at 8 MHz.

Only the required number of bits is transferred for the position value. The bit number can be read out from the encoder for automatic parameterization.

### MEMORY AREAS

The encoder provides several memory areas for parameters. These can be read from by the subsequent electronics, and some can be written to by the encoder manufacturer, the OEM, or even the end user. The parameter data are stored in a permanent memory. This memory permits only a limited number of write access events and is not designed for cyclic data storage. Certain memory areas can be write-protected (this can only be reset by the encoder manufacturer).

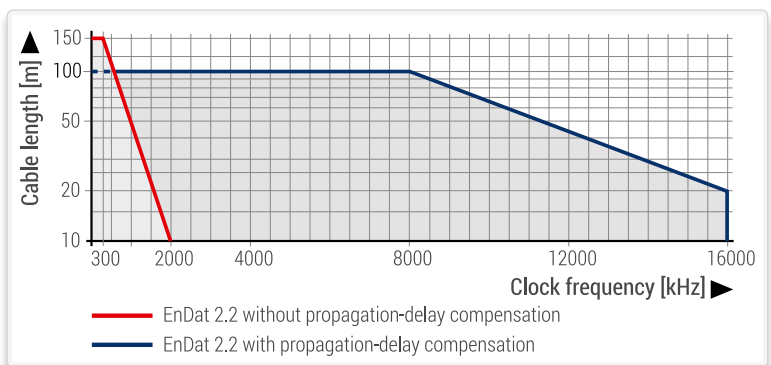
**Parameters** are saved in various memory areas, e.g.:

- Encoder-specific information
- Information of the OEM (e. g. „electronic ID-label“ of the motor)
- Operating parameters (datum shift, instruction, etc.)
- Operating status (alarm or warning messages)

**Monitoring and diagnostic functions** of the EnDat interface make a detailed inspection of the encoder possible.

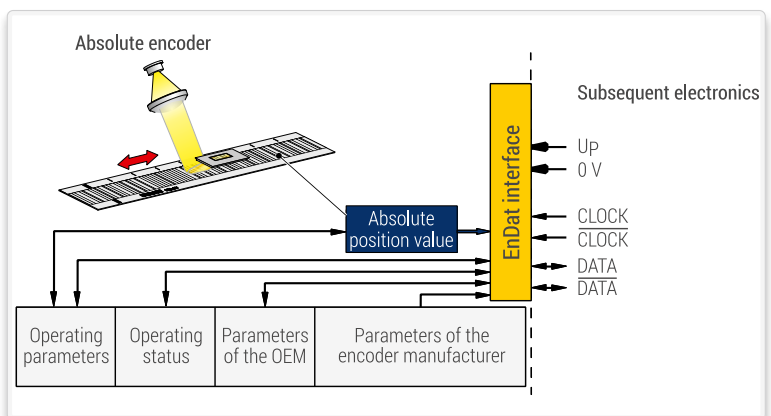
- Error messages
- Warnings
- Online diagnostics based on valuation numbers (EnDat 2.2)

Interface	EnDat 2.2 serial bidirectional
Data transfer	Position values, parameters and additional data
Data input	Differential line receiver according to EIA standard RS 485 for the signals CLOCK, $\overline{\text{CLOCK}}$ , DATA and $\overline{\text{DATA}}$
Data output	Differential line driver according to EIA standard RS 485 for DATA and $\overline{\text{DATA}}$ signals
Position values	Ascending during traverse in direction of cable outlet
Power supply	3.6 V to 14 V



### ADDITIONAL DATA

One or two items of additional data can be appended to the position value, depending on the type of transmission (selection via MRS code). The additional data supported by the respective encoder is saved in the encoder parameters.



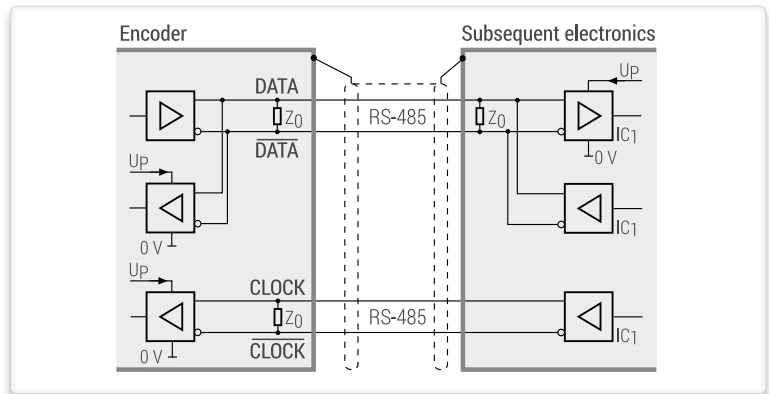
## INPUT CIRCUITRY OF SUBSEQUENT ELECTRONICS

### Dimensioning

IC1 = RS 485 differential line receiver

$Z_0 = 120 \Omega$

EnDat2.2 is a bidirectional interface of HEIDENHAIN.  
Detailed information you will find on: [www.endat.de](http://www.endat.de)



## CUSTOMER-SPECIFIC SERIAL INTERFACES

### BiSS C

RSF Elektronik encoders with the **Code B** after the model designation are suited for connection to BiSS C controls with **BiSS C unidirectional interface** (permissible clock frequencies  $\leq 5$  MHz or 10 MHz)

- Ordering designation: BiSS/Cu

### Fanuc

RSF Elektronik encoders with the **Code F** after the model designation are suited for connection to Fanuc controls with **Fanuc Serial Interface**

- Ordering designation: Fanuc05 ai Interface

### Mitsubishi

RSF Elektronik encoders with the **Code M** after the model designation are suited for connection to Mitsubishi controls with **Mitsubishi high speed interface**

- Ordering designation: Mit03-2  
One-pair transmission
- Ordering designation: Mit03-4  
Two-pair transmission

### Panasonic

RSF Elektronik encoders with the **Code P** after the model designation are suited for connection to Panasonic controls with **Panasonic Serial Interface**

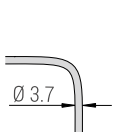
- Ordering designation: Pana02

### Yaskawa

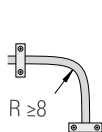
RSF Elektronik encoders with the **Code Y** after the model designation are suited for connection to Yaskawa controls with **Yaskawa Serial Interface**

- Ordering designation: YEC07

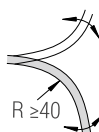
## SHIELDING



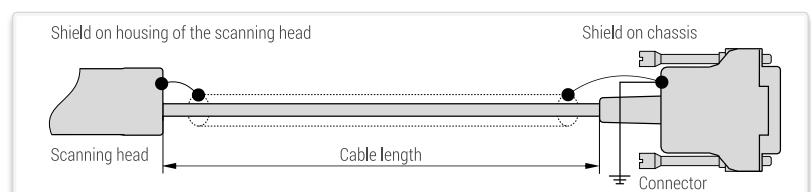
Shielded PUR-cable,  
Drag chain qualified.



Bending radius  
fixed mounting



Bending radius  
continuous flexing



## MC 15 TECHNICAL DATA

### SCANNING HEAD

Model	AK MC 15	AK MC 15 B	AK MC 15 F	AK MC 15 M		AK MC 15 P	AK MC 15 Y
Interface	EnDat 2.2	BiSS C unidirectional	Fanuc serial interface $\alpha$ i Interface	Mitsubishi high speed interface		Panasonic serial interface	Yaskawa serial interface
Version	EnDat 2.2	BiSS/Cu	Fanuc05	Mit03-4	Mit03-2	Pana02	YEC07
Measuring step	0,1 $\mu$ m (100 nm) 0,05 $\mu$ m (50 nm)						
Calculation time $t_{cal}$ Clock frequency	$\leq 5 \mu$ s $\leq 16$ MHz	--	--	--	--	--	--
Traversing speed	$\leq 600$ m/min						
Interpolation error	Approx. $\pm 1 \mu$ m						
Electrical connection	Cable, 1 m or 3 m with M12-connector 8-pin or D-sub connector 15-pin						
Voltage supply	DC 3.6 V to 14 V (3.6 V at least required in the scanning head)						
Power consumption	At 3.6 V: $\leq 950$ mW At 14 V: $\leq 1050$ mW						
Current consumption typ.	At 5 V: 100 mA (without load)						
Vibration 55 Hz to 2000 Hz Shock 6 ms	$\leq 500$ m/s <sup>2</sup> (EN 60 068-2-6) $\leq 1000$ m/s <sup>2</sup> (EN 60 068-2-27)						
Operating temperature Storage temperature	-10 °C to 70 °C -20 °C to 70 °C						
Mass	Scanning head: 12 g (without cable), connecting cable: 22 g/m, connector: M12-connector: 15 g; D-sub connector: 28 g						

### GRADUATION CARRIER

Model	MB MC 15 MK	MC 15 MP	MC 15 GK	MC 15 BK
Graduation carrier	Steel tape scale with adhesive tape	Steel tape scale in aluminum carrier with clamping element	Glass scale with adhesive tape	Glass ceramic scale with adhesive tape
Coefficient of linear expansion	$\alpha \approx 10 \times 10^{-6}/K$	$\alpha \approx 10 \times 10^{-6}/K$	$\alpha \approx 8.5 \times 10^{-6}/K$	$\alpha \approx 0 \times 10^{-6}/K$
Accuracy grade (at 20 °C)	$\pm 15 \mu$ m/m	$\pm 15 \mu$ m/m	$\pm 5 \mu$ m/m	$\pm 5 \mu$ m/m
Measuring length ML	Up to 10 000 mm *	Up to 10 000 mm *	Up to 3140 mm	Up to 1920 mm
Mass	17 g/m	92 g/m + 2 g clamping	55 g/m	57 g/m

\* longer lengths on request.

### CONFORMITIES AND CERTIFICATIONS

RoHS	2011/65/EU, 2015/863/EU
EMV	2014/30/EU
Product-Certifications	UL, CSA, EN, IEC 61010-1

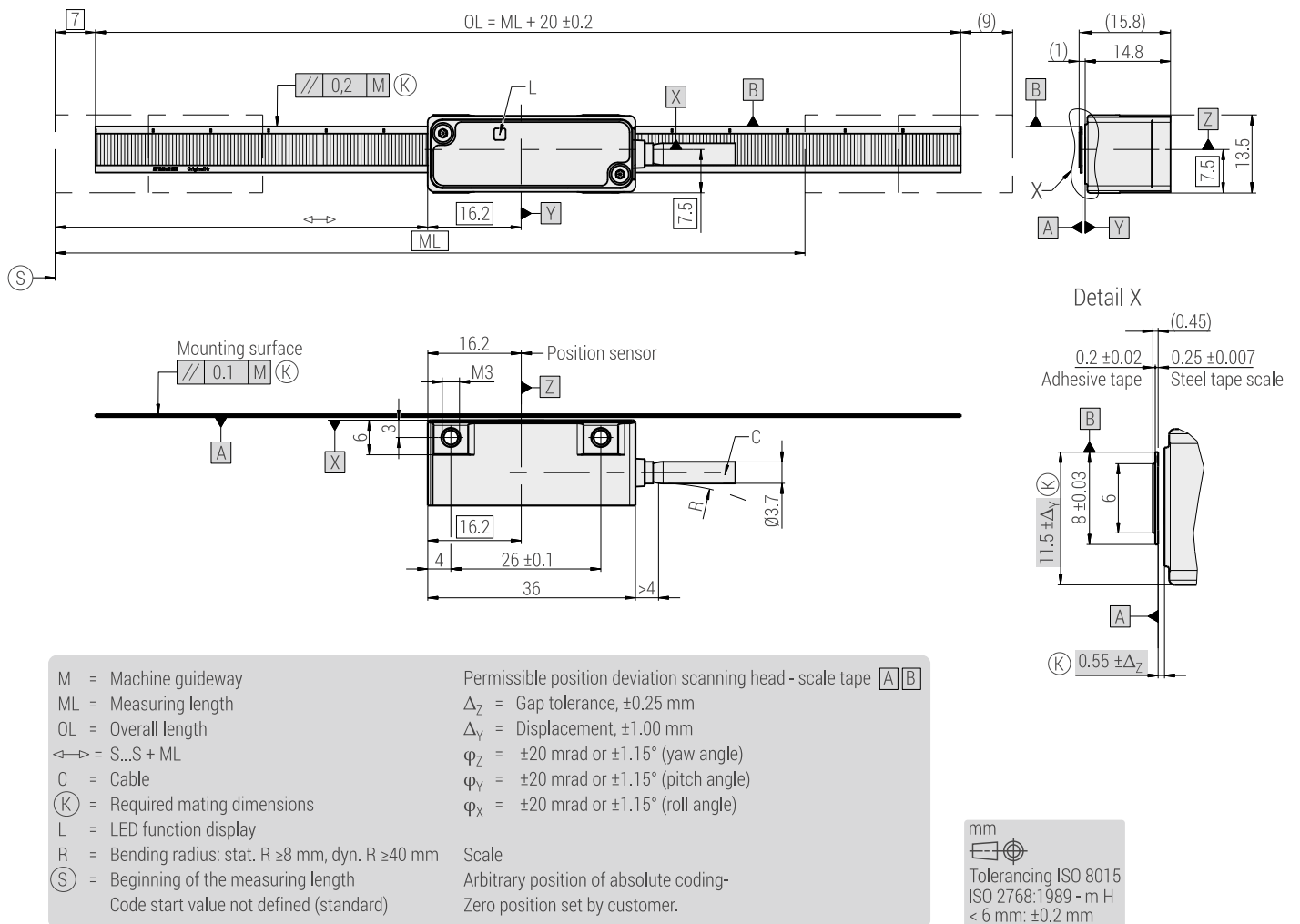


## MC 15 MK

- Steel tape scale with absolute track and adhesive tape



Dimensions, mounting tolerances:



Tape mounting tool **TMT MS 15 MK** (optional)  
For safe and precise mounting of the steel tape scale.

- Mount TMT MS 15 MK instead of the MC 15 scanning head.
- Thread steel tape scale (version MK) and move along the scale length.
- Remove TMT MS 15 MK, mount MC 15 scanning head.

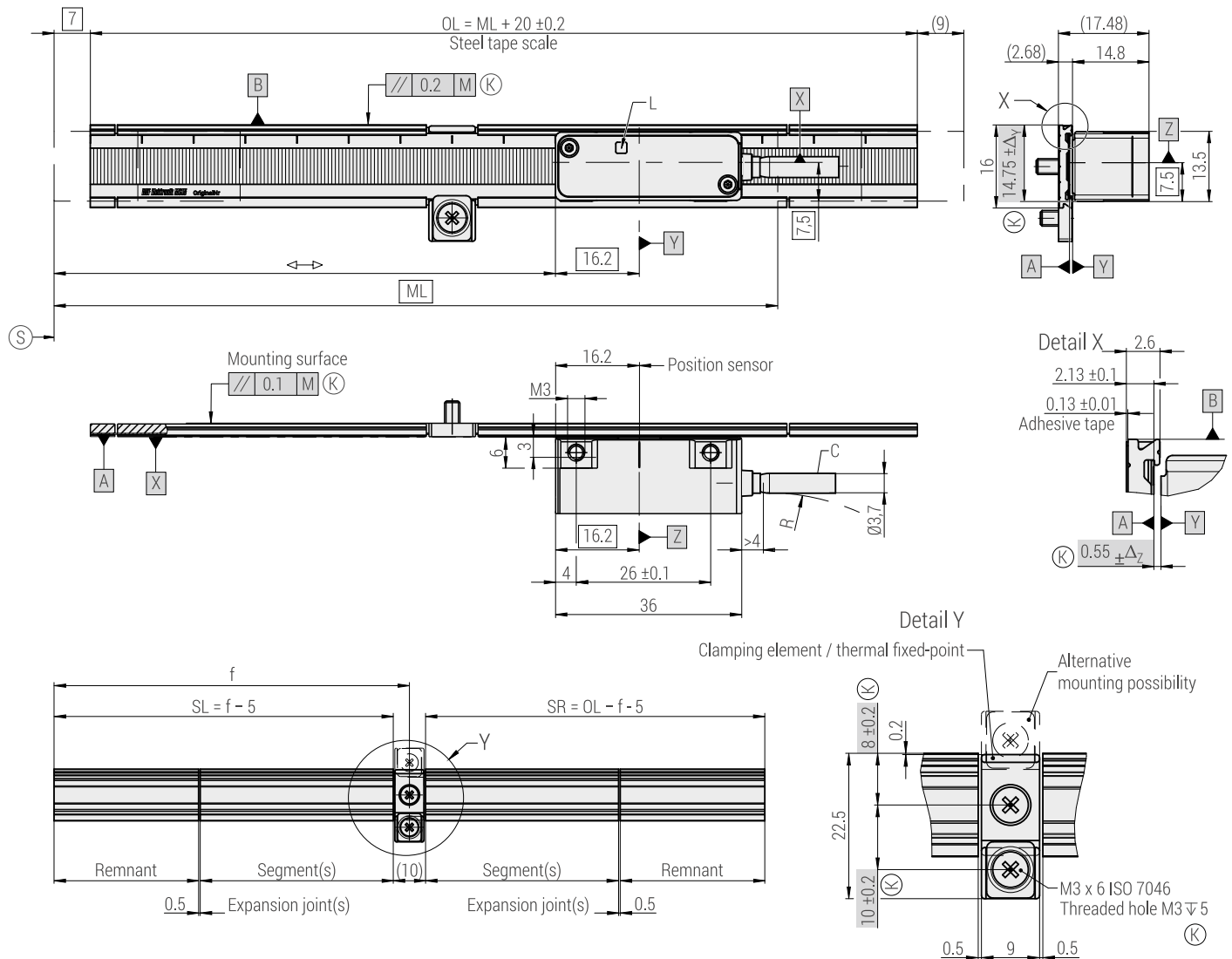


## MC 15 MP

- Steel tape scale with absolute track in aluminum carrier with clamping element
- Clamping element bolted
- Carrier with adhesive tape



Dimensions, mounting tolerances:



M = Machine guideway

ML = Measuring length

OL = Overall length

$$\leftarrow \rightarrow = S \dots S + ML$$

$f$  = Position of the clamping element

Standard:  $f = OL/2$

Optional:  $f = \begin{cases} 4.5 \\ \geq 25 \dots \leq OL - 25 \\ OL - 4.5 \end{cases}$

C = Cable

(K) = Required mating dimensions

L = LED function display

R = Bending radius: stat.  $R \geq 8$  mm, dyn.  $R \geq 40$  mm

(S) = Beginning of the measuring length

Code start value not defined

Permissible position deviation of the scanning head - scale tape 

A	B
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 $\Delta_7$  = Gap tolerance, +0.25 mm / -0.2 mm $\Delta_y$  = Displacement,  $\pm 0.5$  mm
$$\varphi_7 = \pm 20 \text{ mrad or } \pm 1.15^\circ \text{ (yaw angle)}$$
$$\phi_y = \pm 20 \text{ mrad or } \pm 1.15^\circ \text{ (pitch angle)}$$
$$\phi_x = \pm 20 \text{ mrad or } \pm 1.15^\circ \text{ (roll angle)}$$

Scale

Arbitrary position of absolute coding-zero position set by customer.

mm



Tolerancing ISO 8015  
ISO 2768:1989 - m H  
< 6 mm:  $\pm 0.2$  mm

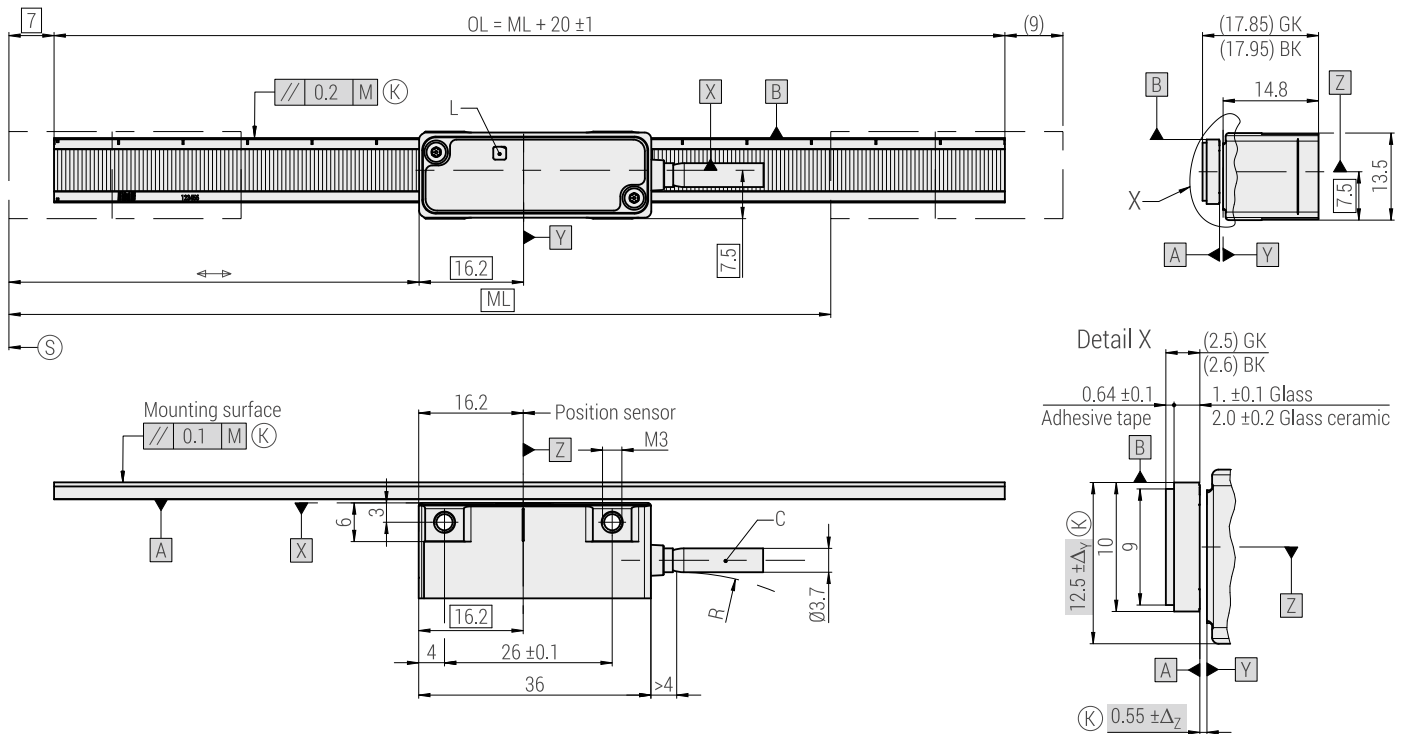


# MC 15 BK, GK

- BK: Glass ceramic scale with absolute track and adhesive tape
- GK: Glass scale with absolute track and adhesive tape



Dimensions, mounting tolerances:



- M = Machine guideway  
ML = Measuring length  
OL = Overall length  
←→ = S...S + ML  
C = Cable  
(K) = Required mating dimensions  
L = LED function display  
R = Bending radius: stat. R ≥ 8 mm, dyn. R ≥ 40 mm  
(S) = Beginning of the measuring length  
Code start value not defined

Permissible position deviation scanning head - scale [A][B]

- $\Delta_Z$  = Gap tolerance,  $\pm 0.25$  mm  
 $\Delta_Y$  = Displacement,  $\pm 1.00$  mm  
 $\varphi_Z$  =  $\pm 20$  mrad or  $\pm 1.15^\circ$  (yaw angle)  
 $\varphi_Y$  =  $\pm 20$  mrad or  $\pm 1.15^\circ$  (pitch angle)  
 $\varphi_X$  =  $\pm 20$  mrad or  $\pm 1.15^\circ$  (roll angle)

Scale  
Arbitrary position of absolute coding -  
zero position set by customer.

mm  
Tolerancing ISO 8015  
ISO 2768:1989 - m H  
< 6 mm:  $\pm 0.2$  mm

## ACCESSORY: EXTERNAL TESTING DEVICE PWT 101

The PWT 101 is a testing device for checking the function and adjustment of absolute RSF Elektronik encoders. Thanks to its compact dimensions and robust design, the PWT 101 is ideal for mobile use. A 4.3-inch touchscreen provides for display and operation.

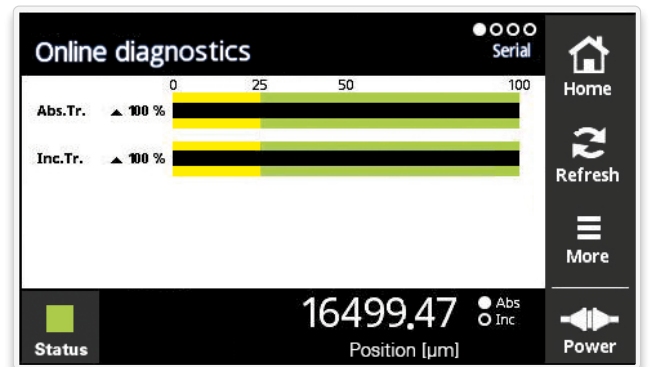
For example, for encoders with EnDat interface you can not only display the position value but also export the online diagnosis, shift datums, and perform further inspection functions.

### AVAILABLE FUNCTIONS

The performance range of the PWT 101 can be expanded by firmware update. Appropriate firmware files that can be imported to the PWT 101 through a memory card (not included in delivery) will be made available at [www.heidenhain.de](http://www.heidenhain.de).



Feature content of the PWT 101	EnDat 2.2	BiSS/Cu	Fanuc05	Mitsubishi 03-4, 03-2	Panasonic02	YEC 07
<b>Position display</b>						
Display of the absolute position	✓	✓	✓	✓	✓	✓
Display and resetting of error messages	✓	✓	✓	✓	✓	✓
Display and resetting of warnings	✓	✓	✓	✓	✓	✓
Display of transmission status	✓	✓	✓	✓	✓	✓
<b>Diagnostics</b>						
Display of online diagnostics	✓	✓	✓	✓	✓	✓
Display of supply voltage and supply current	✓	✓	✓	✓	✓	✓
<b>Additional functions (if supported by the encoder)</b>						
Datum shift („electrical zeroing of position“)	✓	-	-	-	-	-
<b>Memory contents</b>						
Display of encoder information	✓	✓	✓	✓	✓	✓



## STATUS DISPLAY VIA LED FUNCTION

LED function at the scanning head	EnDat 2.2	BiSS/Cu	Fanuc05	Mitsubishi 03-4, 03-2	Panasonic02	YEC 07	Note
<b>GREEN</b> Very good	✓	✓	✓	✓	✓	✓	
<b>YELLOW</b> Warning	✓	✓	-	-	✓	-	Check mounting, clean encoder
<b>RED</b> Alarm	✓	✓	✓	✓	✓	✓	Check mounting, clean encoder

## FURTHER PRODUCTS



### MCR 15 | MCS 15

*Absolute modular angle encoders with small dimensions*

- Diverse serial interfaces
- Status display directly at the scanning head via LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR): 50.00 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR): 59.93 mm to 350.23 mm (outside)
- Possible scanning diameter (MCS): from 75 mm



### MSR 15 | MSS 15

*Incremental modular angle encoders with small dimensions*

- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR): 50.00 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR): 59.93 mm to 350.23 mm (outside)
- Possible scanning diameter (MSS): from 75 mm



### MSR 45

*Modular angle encoders with steel tape scale - various versions*

- Full-circle or segment version
- Grating period: 200 µm
- Accuracy of the grating (stretched): ±30 µm/m
- High permissible rotational speed resp. circumferential speed
- Integrated subdividing: up to times 100
- Possible diameter: Full-circle from Ø 146.99 mm  
Segment from Ø 150 mm



### MS 15

*Exposed linear encoders with integrated mounting control*

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Two independent switch tracks for individual special functions
- Position of reference mark selectable by customer
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 200
- Max. measuring length: Steel tape scale: 20 000 mm  
Glass scale: 3140 mm



### MS 25

*Exposed scanning linear encoders with integrated mounting control*

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Two independent switch tracks for individual special functions
- Position of reference mark selectable by customer
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 200
- Max. measuring length: Glass scale: 3140 mm  
Steel tape scale: 20 000 mm



### MS 45

*Exposed linear encoders with integrated mounting control*

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Flat dimensions
- Easy mounting due to large mounting tolerances
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 100
- Max. measuring length: Steel tape scale: 30 000 mm

## DISTRIBUTION CONTACTS

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Date 05/2023 ■ Art.No. 1210495-04 ■ Doc.No. D1210495-05-C-01 ■ Technical adjustments in reserve!



# RSF Elektronik

Ges.m.b.H.

Linear and Angle Encoders  
Precision Graduations

Certified acc. to  
ISO 9001  
ISO 14001



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