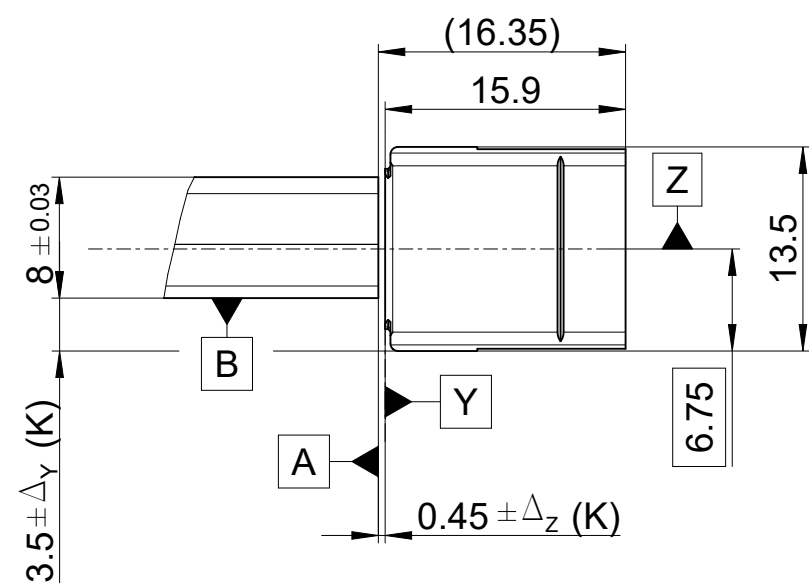
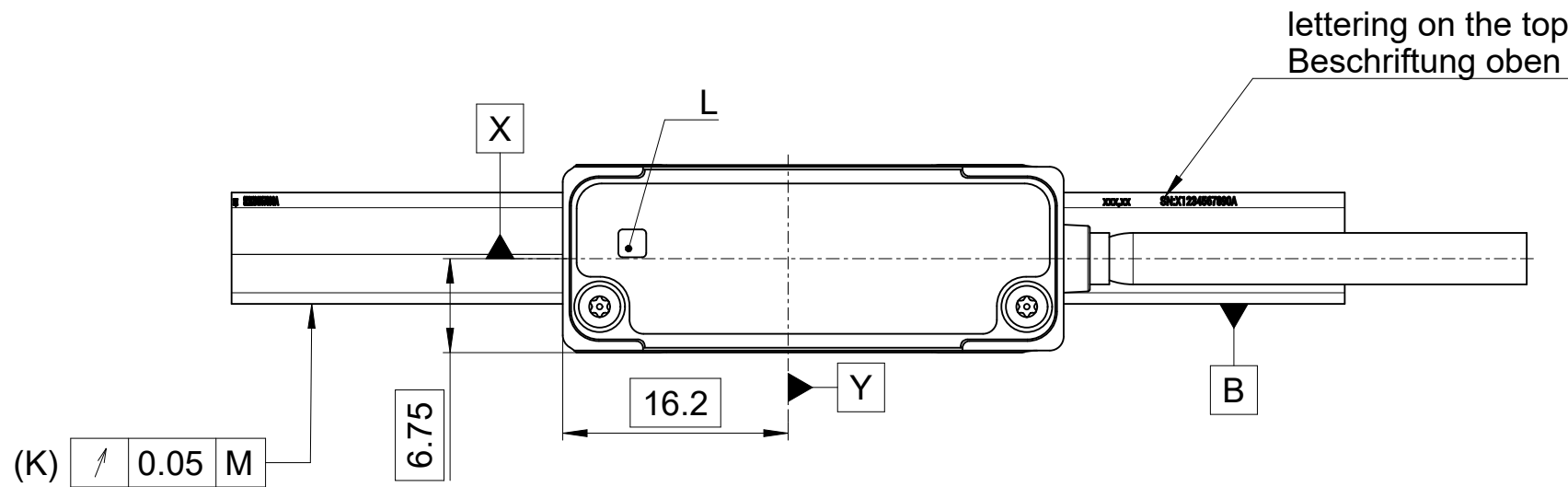
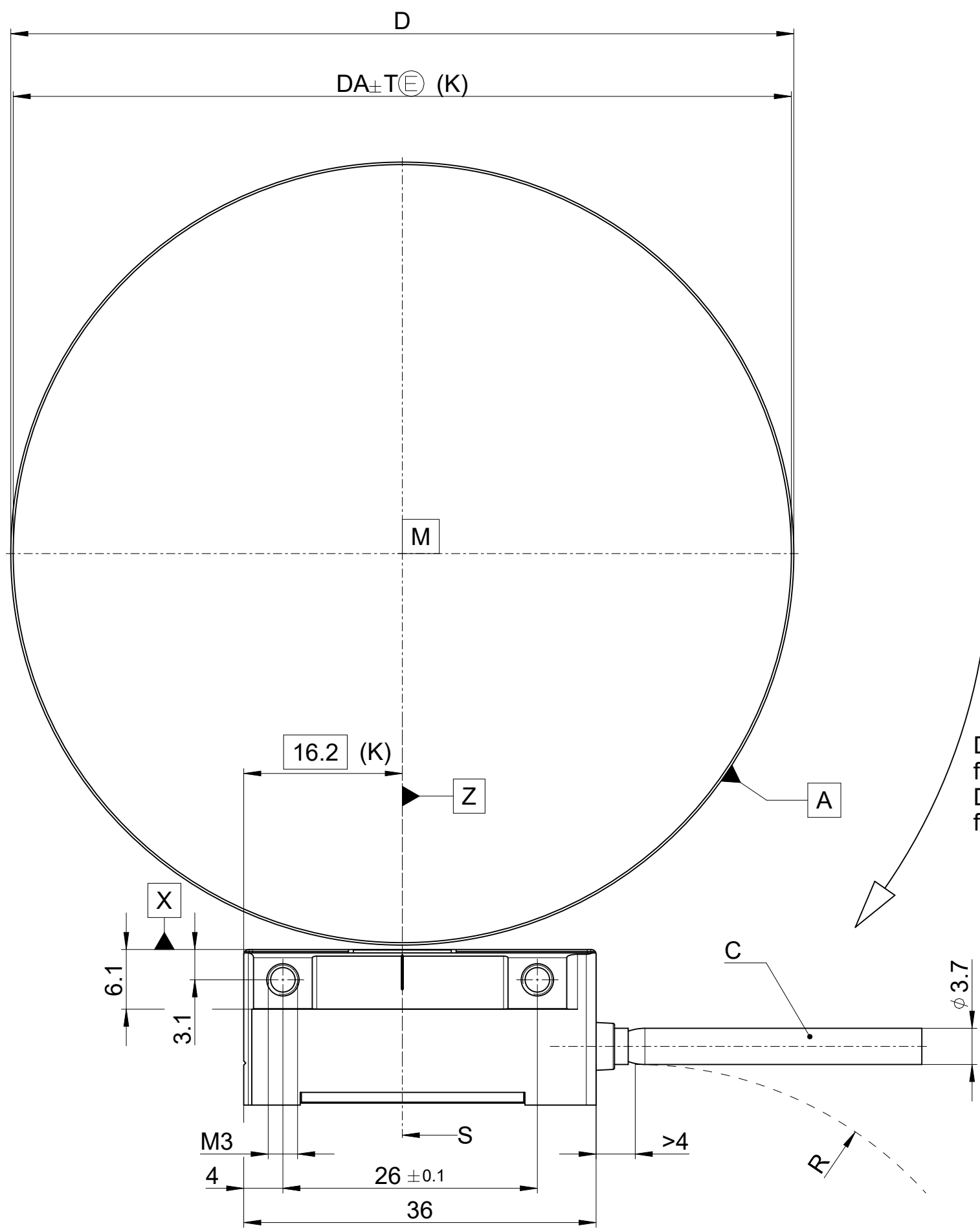




D	±T
>Ø75.00 - ≤ Ø80.00	0.008
>Ø80.00 - ≤ Ø120.00	0.010
>Ø120.00 - ≤ Ø180.00	0.015
>Ø180.00 - ≤ Ø250.00	0.020
>Ø250.00 - ≤ Ø370.00	0.030
>Ø370.00 - ≤ Ø500.00	0.045
>Ø500.00 - ≤ Ø660.00	0.060
>Ø660.00	0.080



$DA = D - 0.5$

M = rotary axis / Rotationsachse

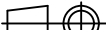
D = scanning diameter / Abtastdurchmesser
DA = mating diameter / Aufnahme Durchmesser
T = tolerance mating diameter / Toleranz Aufnahme Durchmesser

S = optical centerline and mark for 0° position
optische Mittellinie und Markierung für 0° position
C = cable / Anschlusskabel
K = customer mounting dimensions / kundenseitige Anschlussmaße
R = bending radius / Biegeradius: stat. $R \geq 8\text{mm}$, dyn. $R \geq 40\text{mm}$
L = LED function display / LED Funktionsanzeige

Permissible position deviation scanning head - tape scale ring A B
Zulässige Lageabweichungen Abtasteinheit - Maßbandring A B

$\varphi_z = \pm 5\text{mrad}$ or / oder $\pm 0.29^\circ$ (yaw angle / Gierwinkel)
 $\varphi_y = \pm 5\text{mrad}$ or / oder $\pm 0.29^\circ$ (pitch angle / Nickwinkel)
 $\varphi_x = \pm 7\text{mrad}$ or / oder $\pm 0.40^\circ$ (roll angle / Rollwinkel)

Δ_z = (GAP tolerance / Abstandstoleranz)
= $\pm 0,1 \dots D \leq 110$
= $\pm 0,15 \dots D > 110$
 Δ_y = $\pm 0,5$ (displacement / Verschiebung)

					ID number:						
					Change No. C157360-42						
					Phase: Serie						
	Original drawing		MCR16 MBR MCR16 MBR Anschlussmaße / Mating Dimensions								
	Scale	Format									
Dimensions in mm	2:1	A2	General Tolerances ISO 2768:1989-mH ≤ 6:±0.2								
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							Document number				